## BIOS 760 Final, 2012: Solution

1. (a) Using the change of variable  $v = x - \theta$ , we obtain that

$$\int_{R} f_{\theta}(x) dx = \int_{\theta}^{\infty} e^{-(x-\theta)} dx = \int_{0}^{\infty} e^{-v} dv = 1.$$

The full likelihood has the form

$$\prod_{i=1}^{n} f_{\theta}(X_i) = \exp\left[\sum_{i=1}^{n} X_i\right] e^{n\theta} \mathbb{1}\{X_{(1)} > \theta\}$$
$$= a(X_1, \dots, X_n) b(\theta, X_{(1)}),$$

and thus  $X_{(1)}$  is sufficient by factorization.

(b) The density of the smallest order statistic in an i.i.d. sample with density  $f_{\theta}(x)$ , where we let  $F_{\theta}(x)$  be the corresponding c.d.f., is

$$nf_{\theta}(x)(1-F_{\theta}(x))^{n-1} = ne^{-(x-\theta)}\exp[-(n-1)(x-\theta)],$$

and the given form of the density follows. Now let  $\gamma(x)$  be an arbitrary measurable integrable function, and note that for any  $\theta \in R$ ,

$$\int_{R} \gamma(x) g_{\theta}(x) dx = 0 \quad \Rightarrow \quad \int_{\theta}^{\infty} \gamma(x) n e^{-n(x-\theta)} dx = 0,$$

which implies that

$$\int_{\theta}^{\infty} \gamma(x) e^{-nx} dx = 0 \quad \Rightarrow \quad \gamma(\theta) e^{-n\theta} = 0,$$

where the last equality follows from differentiating both sides of the left-hand equality with respect to  $\theta$ . This now implies that  $\gamma(\theta) = 0$  for all  $\theta \in R$ . Thus  $X_{(1)}$  is complete since  $\gamma(x)$  was arbitrary.

(c) The expectation of  $X_{(1)}$  is

$$\int_{\theta}^{\infty} x n e^{-n(x-\theta)} dx = \theta + \int_{R} n(x-\theta) e^{-n(x-\theta)} dx$$
$$= \theta + n^{-1} \int_{0}^{\infty} v e^{-v} dv$$
$$= \theta + n^{-1},$$

where the second-to-last equality uses the change of variables  $v = n(x - \theta)$ . Thus, since  $X_{(1)}$  is complete and sufficient for  $\theta$ , the UMVU of  $\theta$  is  $X_{(1)} - n^{-1}$ . 2. (a) Since the log-likelihood for a single observation is  $\ell(p) = \log [pU + (1-p)(1-U)]$ , the corresponding score and information for the sample are

$$\dot{\ell}_n(p) = \sum_{i=1}^n \frac{2U_i - 1}{pU_i + (1-p)(1-U_i)}$$

and

$$I_n(p) = -\ddot{\ell}_n(p) = \sum_{i=1}^n \frac{(2U_i - 1)^2}{\left[pU_i + (1 - p)(1 - U_i)\right]^2}$$

(b) The result follows directly from the standard Newton-Raphson iteration formula for the sample log-likelihood:

$$p^{(k+1)} = p^{(k)} + \left[I_n(p^{(k)})\right]^{-1} \dot{\ell}_n(p^{(k)}).$$

(c) The form of  $m_p(\delta, u)$  follows directly from the mixture structure. The marginal density for U is obtained by summing over  $\delta$  (corresponding to the  $\Delta$  component) which yields that the marginal is  $h_p(u)$ . The form of the sample log-likelihood follows directly from the log-likelihood for a single observation obtained from  $m_p(\delta, u)$ , which is

$$\log(2) + \Delta \left[ \log(p) + \log(U) \right] + (1 - \Delta) \left[ \log(1 - p) + \log(1 - U) \right].$$

(d) The expectation of  $\Delta_i$ , given  $U_i$  at the value  $p = p^{(k)}$ , is the same as the probability that  $\Delta_i = 1$ , given  $U_i$  evaluated at  $p = p^{(k)}$ , which is

$$\frac{m_{p^{(k)}}(1,U_i)}{\sum_{\delta=0,1}m_{p^{(k)}}(\delta,U_i)} = \frac{p^{(k)}U_i}{p^{(k)}U_i + (1-p^{(k)})(1-U_i)}.$$

(e) The expectation of the full sample log-likelihood, with individual components having the from in (c) above, given the observed data, after throwing out the constant log(2), has the form

$$E\left[\sum_{i=1}^{n} \Delta_{i} \left[\log(p) + \log(U_{i})\right] + (1 - \Delta_{i}) \left[\log(1 - p) + \log(1 - U_{i})\right] \middle| Y_{obs}, p^{(k)}\right]$$
  
= 
$$\sum_{i=1}^{n} E\left\{\Delta_{i} \left[\log(p) + \log(U_{i})\right] + (1 - \Delta_{i}) \left[\log(1 - p) + \log(1 - U_{i})\right] \middle| U_{i}, p^{(k)}\right\}$$
  
= 
$$\sum_{i=1}^{n} W_{k}(U_{i}) \left[\log(p) + \log(U_{i})\right] + (1 - W_{k}(U_{i})) \left[\log(1 - p) + \log(1 - U_{i})\right],$$

where the second equality follows from the independence across observation. Now differentiate the last term above with respect to p, to obtain that the next EM update  $p^{(k+1)}$  is the solution of

$$\sum_{i=1}^{n} \left[ \frac{W_k(U_i)}{p} - \frac{1 - W_k(U_i)}{1 - p} \right] = 0,$$

and the desired conclusion follows.

(f) In the EM algorithm, if  $p^{(k)} = 0$ , then  $p^{(k+1)} = 0$  and the EM iteration is stuck at zero. For the Newton-Raphson iteration,  $p^{(k+1)}$  is almost surely not zero if  $p^{(k)} = 0$ . This says that the EM has faulty local solutions which need to be avoided or worked around in the estimation process. The Newton-Raphson algorithm appears to not have this problem.